

A New Method for the Optimization of Optical Systems: Comparisons and Discussions

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Step Optimization (STP)

- Synopsys has implemented a new, optional algorithm for local optimization that can:
 - Speed up convergence
 - Find a better local minimum (smaller Error Function) compared to standard optimization
- It is called "Step Optimization" because it sometimes not always - progresses in a step-wise manner, as shown on the next slide



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STEP Optimization (STP)

Sometimes converges in a step-wise manner



Microscope Example







Microscope Example

Standard Optimizer



After Optimization

(Both methods found this same solution)







Microscope Example

Comparison of STP and Standard



Complex Error Function Spaces

- Even comparatively simple systems can have complex error functions
- The 2-dimensional error function space formed by the two curvatures shown in red at the lens below has 4 distinct local minima, as shown on the next slide







2-D Error function space

Formed by two adjacent curvatures



Palaiseau, 22.01.2014

Step Optimization Can Help Find a Better Local Minimum in Complex ERF Space



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Off-Axis Ellipse







Necessary Variables

- This is a good test problem: We know there is one exact solution
- For an optimizer, this is a tricky problem, as the following parameters must be simultaneously varied in such a way that the physical surface remains at the center of the aperture
 - Radius
 - Conic Constant
 - Y-Position
 - Z-Position
 - Tilt Angle
- These parameters are all individually very sensitive
 - A change to any one of these parameters increases the merit function severely
- The optimization problem is a "long, narrow valley" in 5 dimensions



Off Axis Ellipse

Standard Optimizer



Off-Axis Ellipse

After Optimization







Off Axis Ellipse Comparison of STP and Standard



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Error Function Plot

Three Mirror System

Rotationally Symmetric Aspheres







Freeform Optimization

- Each mirror has 17 aspheric coefficients varying, plus radius and tilt
 - The number of degrees of freedom is large because it is a 2D problem
- It is necessary to use a large number of field points (25 used here)
 - Otherwise, we might obtain good performance at the sample points and terrible performance between the sample points
 - We used 25 field points: roughly 5 times more fields than we would in a rotationally symmetric design
- The optimization tends to be slow... any convergence acceleration is greatly appreciated!





Three Mirror System

Standard Optimizer



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Three Mirror System Reoptimized with Freeform (Zernike) Surfaces



Both optimizers found this same solution... But in how many cycles?





Three Mirror System

Comparison of STP and Standard



Lithography Example







Optimization Characteristics

- Lithography lenses are characterized by having extremely narrow "valleys" in a highly multidimensional space
 - Hundreds of variables (134 in the example shown here)
 - NA 0.9 (or faster): Each variable has a very large effect on the merit function
 - A small change in any variable can be almost perfectly compensated by changes in the other 133 variables
- Lithography lenses are notoriously slow to optimize
 - Infinitesimal improvement per cycle
 - Many thousands of cycles needed, just to see if a design approach is working or not working



Lithography Example Standard Optimizer



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Error Function Plot, 22 Element Litho Lens

Lithography Example

Comparison of STP and Standard



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Error Function Plot, 22 Element Litho Lens

Summary

- The new step optimization (STP) is very useful for speeding up convergence, particularly in problems with complex solution spaces
- STP is a local optimizer, but it sometimes finds deeper local minima – an added bonus
- STP is not a replacement for Global Synthesis (GS), but it can be used within GS to speed the convergence of GS



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